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*Huang, J.; Tomizuka, M.;*

Mechatronics, IEEE/ASME Transactions on , Volume: 10 , Issue: 1 , Feb. 2005

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**2 An H-infinity-based control design methodology dedicated to the active control of vehicle longitudinal oscillations**

*Lefebvre, D.; Chevrel, P.; Richard, S.;*

Control Systems Technology, IEEE Transactions on , Volume: 11 , Issue: 6 , Nov. 2003

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**3 Problem of precision missile guidance: LQR and H/sup /spl infin// control frameworks**

*Savkin, A.V.; Pathirana, P.N.; Faruqi, F.A.;*

Aerospace and Electronic Systems, IEEE Transactions on , Volume: 39 , Issue: 3 , July 2003

Pages:901 - 910

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**4 Editorial: Why H-infinity?**

*Haddad, A.;*

Automatic Control, IEEE Transactions on , Volume: 32 , Issue: 10 , Oct 1987

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**5 Semi-decentralized adaptive fuzzy control for cooperative multirobot systems with H<sup>∞</sup> motion/internal force tracking performance**

*Kuang-Yow Lian; Chian-Song Chiu; Liu, P.;*